SCAG Activity-based Model Update

Hsi-Hwa Hu, Bayarmaa Aleksandr SCAG Modeling & Forecasting Department

> SCAG Modeling Task Force March 29, 2018



Outline

Introduction

Tasks completed – Phase 1

Current status – Phase 2

Future tasks – Phase 3

MTF meeting, March 29, 2018

Objectives



MTF meeting, March 29, 2018

SCAG ABM

- Based on past works and analyses
- More than 40 sub-models
- Adopt CT-ramp platform and software
 - Coordinated Travel -Regional Activity Modeling Platform
- Integrate with TransCAD static assignment
 - * ABM will generate OD matrices as input for assignment procedure
- Rich output data for policy analysis

SCAG ABM Framework

- Population synthesis
- Long-term location & arrangements
- Mid-term mobility attributes
- Day-level activity, tour & time
- Tour-level details
- Trip-level details



Project Plan and Schedule



Phase 1 Development (03/17 ~ 12/17)

- ✓ Completed on schedule
- ✓ Software development
- ✓ Initial sub-model calibration and validation
- ✓ Software test with 20% sample
- ✓ Scenario test with 10% sample
- ✓ Initial test results are reasonable

Software testing

- Exposing and resolving run-time errors
- ✓ Testing model with :
 - >different household samples
 - >different random number seeds
 - >different hardware environments
 - >different scenario inputs

Run Time for One Loop with 10% Sample



36.3 Hours (20%) **/ 28.8 Hours** (10%) One pass. Not include time for HDT model (0.5 hr)

Scenario Tests

- Test whether the model generates reasonable output
- > 2016 RTP/SCS scenarios: 2012, 2040 baseline, 2040 plan
- > 2020 RTP/SCS scenario: 2016 (draft SED)
- Model output comparison: ABM vs. TBM
 - ≻ Regional VMT, VHT
 - > Vehicle Trips, OD between SCAG counties
 - > Average speeds

Scenario test results* – Vehicle Trips

Total vehicle trips within 4% of tripbased model estimate



• Model results are preliminary and the model used from Phase I work for the runs requires further calibration and validation

Scenario test results* - VMT

Vehicle-miles travelled for light and medium-duty vehicles

- 2016 within 10%
- 2040B within 2%
- 2040P within 6%



* Model results are preliminary and the model used from Phase I work for the runs requires further calibration and validation

Scenario test results* - VHT

Vehicle-hours travelled for light and medium-duty vehicles:

- 2016 within 20%
- 2040B within 5%
- 2040P within 10%

Deviation due to incomplete time of day model calibration



* Model results are preliminary and the model used from Phase I work for the runs requires further calibration and validation

Scenario test results* - Speed



* Model results are preliminary and the model used from Phase I work for the runs requires further calibration and validation

Scenario test results* - OD

ABM - 2016							
CNTY	IM	LA	OR	RV	SB	VC	Sum
IM	97%	0%	0%	3%	0%	0%	100%
LA	0%	92%	5%	0%	2%	1%	100%
OR	0%	13%	84%	2%	1%	0%	100%
RV	0%	2%	3%	87%	8%	0%	100%
SB	0%	8%	2%	8%	81%	0%	100%
VC	0%	14%	0%	0%	0%	86%	100%

TBM - 2016							
CNTY	CNTY IM		OR	RV	SB	VC	Sum
IM	98%	0%	0%	2%	0%	0%	100%
LA	0%	92%	5%	1%	2%	1%	100%
OR	0%	13%	83%	2%	1%	0%	100%
RV	0%	3%	3%	86%	9%	0%	100%
SB	0%	9%	2%	9%	80%	0%	100%
VC	0%	12%	0%	0%	0%	87%	100%

ABM - 2040 Baseline

CNTY	IM	LA	OR	RV	SB	VC	Sum
IM	95%	0%	0%	4%	1%	0%	100%
LA	0%	93%	4%	0%	2%	1%	100%
OR	0%	12%	85%	2%	1%	0%	100%
RV	1%	2%	2%	88%	7%	0%	100%
SB	0%	8%	2%	9%	81%	0%	100%
VC	0%	11%	0%	0%	0%	88%	100%

TBM - 2040 Baseline

CNTY	IM	LA	OR	RV	SB	VC	Sum
IM	97%	0%	0%	2%	0%	0%	100%
LA	0%	92%	4%	1%	2%	1%	100%
OR	0%	12%	84%	2%	1%	0%	100%
RV	0%	2%	2%	88%	8%	0%	100%
SB	0%	7%	2%	9%	82%	0%	100%
VC	0%	11%	0%	0%	0%	88%	100%

ABM - 2040 Plan

CNTY	IM	LA	OR	RV	SB	VC	Sum	
IM	95%	0%	0%	4%	1%	0%	100%	
LA	0%	93%	4%	1%	2%	1%	100%	
OR	0%	12%	85%	2%	1%	0%	100%	
RV	1%	2%	2%	88%	7%	0%	100%	
SB	0%	8%	2%	9%	81%	0%	100%	
VC	0%	11%	0%	0%	0%	88%	100%	

TBM - 2040 Plan

_								
	CNTY	IM	LA	OR	RV	SB	VC	Sum
	IM	98%	0%	0%	2%	0%	0%	100%
	LA	0%	92%	4%	1%	2%	1%	100%
	OR	0%	12%	85%	2%	2%	0%	100%
	RV	0%	2%	2%	88%	8%	0%	100%
	SB	0%	7%	2%	9%	82%	0%	100%
	VC	0%	10%	0%	0%	0%	89%	100%

* Model results are preliminary and the model used from Phase I work for the run requires further calibration and validation

Phase 2 (01/2018 ~ 06/2018)

Model software enhancement

- Run-time optimization
- Automated error checking and model output reporting

System-wide model validation

- 2017 RTP Guideline
- Highway & Transit

Graphic user interface

Sensitivity Test

Model output analysis

Model documentation and user training

Phase 3 (07/2018 ~ 12/2018)

Peer review workshop Fall, 2018

Continue model enhancement and testing Continue model software enhancement

Thank you.

Hsi-Hwa Hu <u>hu@scag.ca.gov</u> Bayarmaa Aleksandr <u>Aleksandr@scag.ca.gov</u>